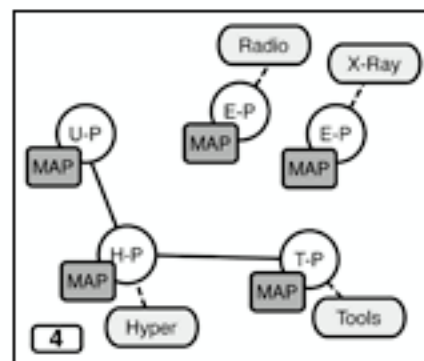


IEEE Transactions on Services Computing (TSC)

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By Adam Barker, Christopher D. Walton, and David Robertson




This paper introduces the Multiagent Protocols (MAP) Web service choreography language and demonstrates how service choreographies can be specified, verified, and enacted with a comparatively simple process language. MAP is a directly executable specification, services do not have to be preconfigured at design-time. Instead, a choreography, specified in MAP, can be sent dynamically to a group of distributed peers to execute at runtime. Furthermore, MAP is based on a formal foundation, this allows model checking of the choreography definition prior to live distribution and enactment.

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